

Launch Name: Sample South Run

Robot Start Position: South corner facing west

Step #	Pseudocode
1	Move straight along south wall (20 inches)
2	Keep motor on and move until color sensor sees black line
3	Use both color sensors to align on the black line
4	Move 1 more inch straight
5	Lower motor rapid (100 power) quickly to hit lever
6	Repeat step 5 three times. Wait one sec in between each attempt
7	Raise arm
8	Move backwards into base (20 inches + 10 Inches to make sure it is base)



Launch Name:

Robot Start Position:

Step #	Pseudocode	
1		
2		
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13		
14		

Robot Start Position:



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